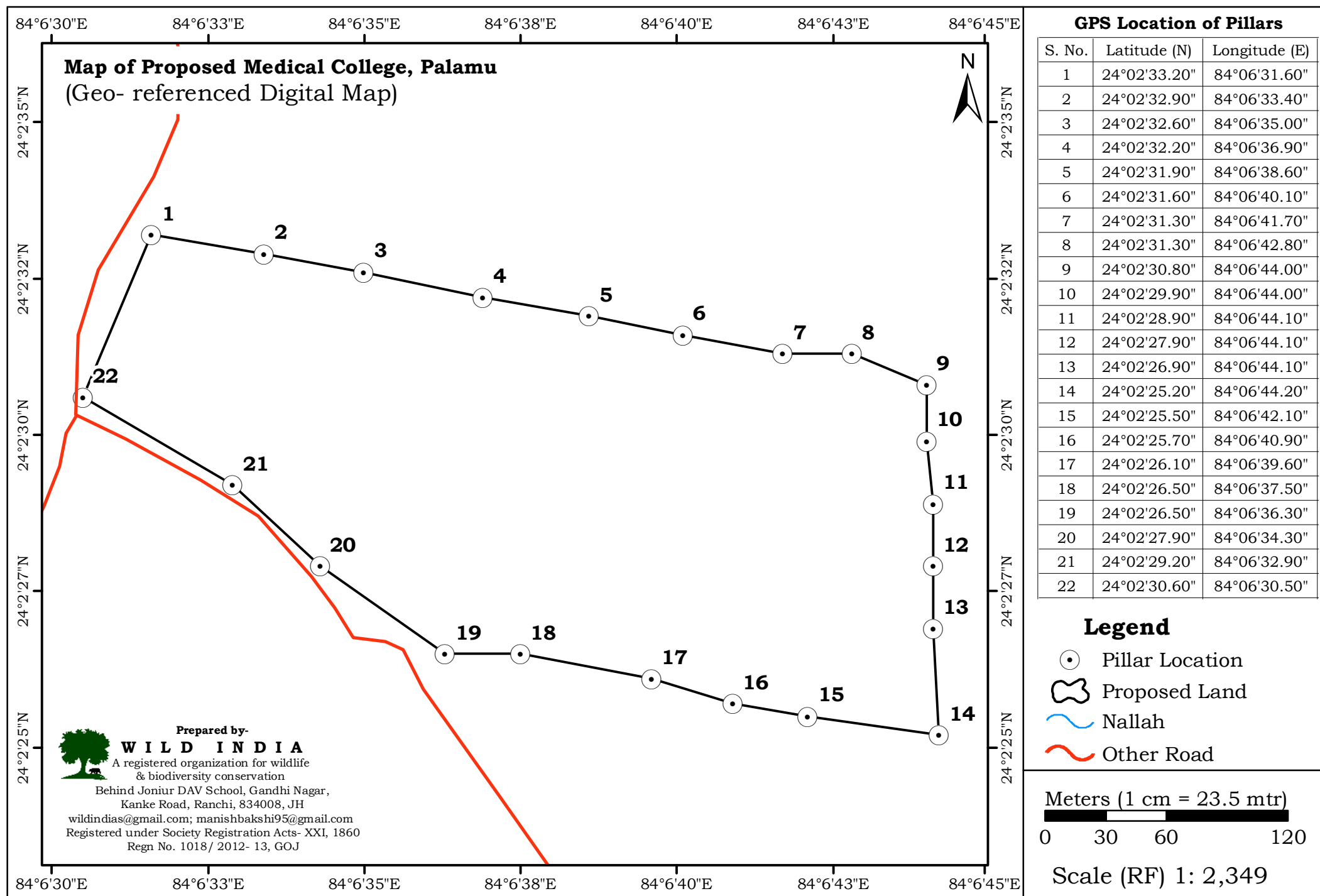




Map is based on survey of marked pillars. Garmin OREGON 550 (±3 m) GPS used.